





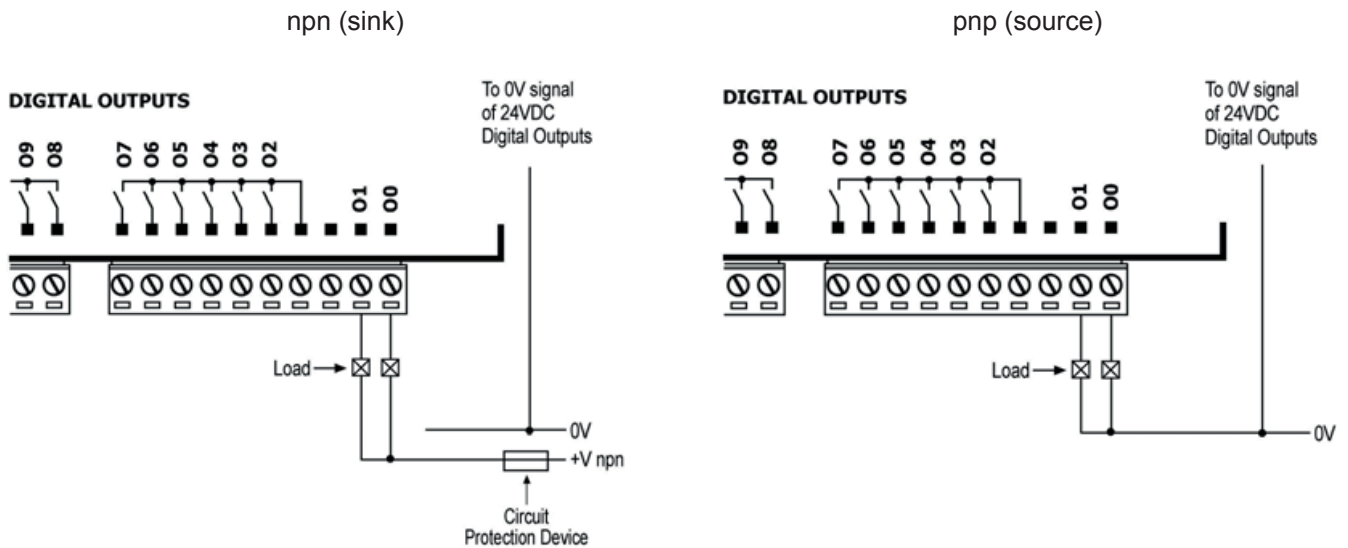






### Transistor Outputs

- Each output can function as either npn or pnp, in accordance with jumper settings and wiring. Open the device and set the jumpers according to the instructions beginning on page 8.
- The 0V signal of the transistor outputs is isolated from the controller's 0V signal.



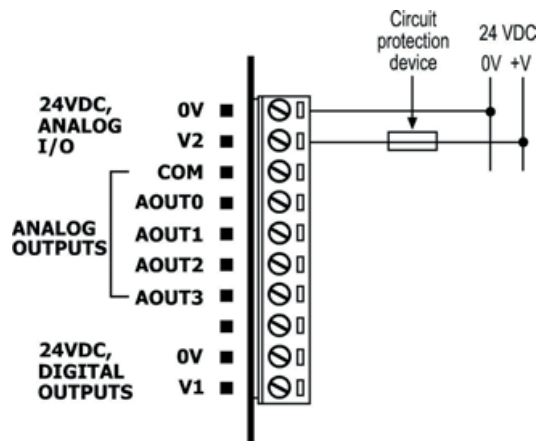
### Analog I/O Power Supplies

Use a 24VDC power supply for all analog input and output modes.

- Connect the "positive" cable to the "V2" terminal, and the "negative" to the "0V" terminal.
- In the event of voltage fluctuations or non-conformity to voltage power supply specifications, connect the device to a regulated power supply.
  - Since the analog I/O power supply is isolated, the controller's 24VDC power supply may also be used to power the analog I/Os.



The 24VDC power supply must be turned on and off simultaneously with the controller's power supply.

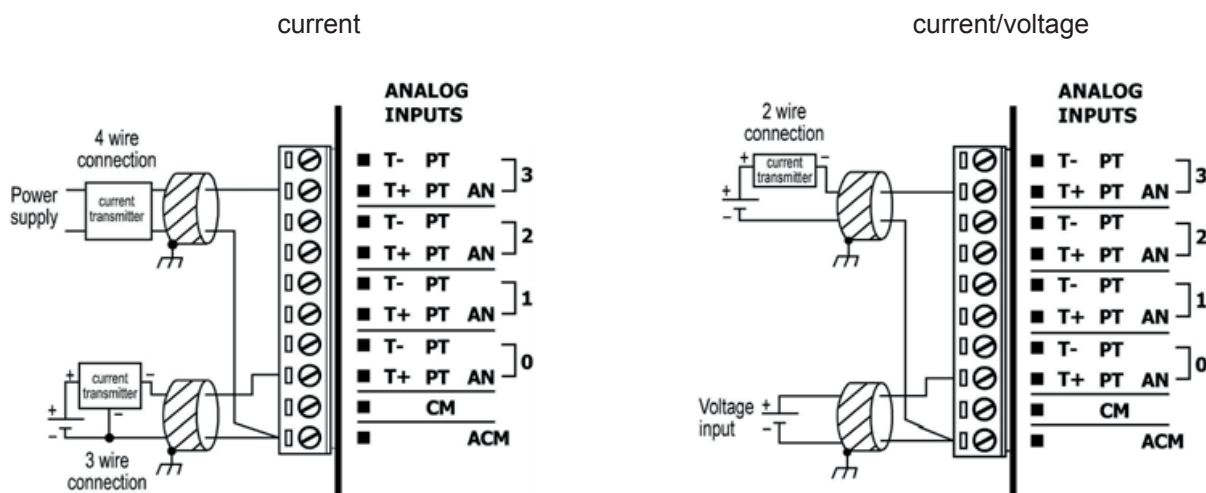


### Analog / PT100 / TC Inputs

- Each input may be set as either analog, RTD, or thermocouple. To set an input:
  - Use the appropriate wiring as shown below.
  - Open the device and set the jumpers according to the instructions beginning on page 8.
- Shields should be connected at the signal source.
- In order to function correctly, the analog power supplies must be wired as shown on page 5.
- To ensure proper performance, a warm-up period of a half an hour is recommended.

### Analog Inputs

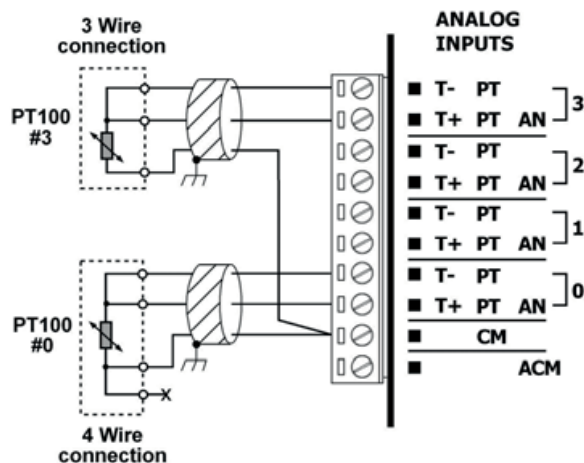
- Inputs may be wired to work with either current or voltage.
- When set to current/voltage, all inputs share a common ACM signal.



### RTD Inputs

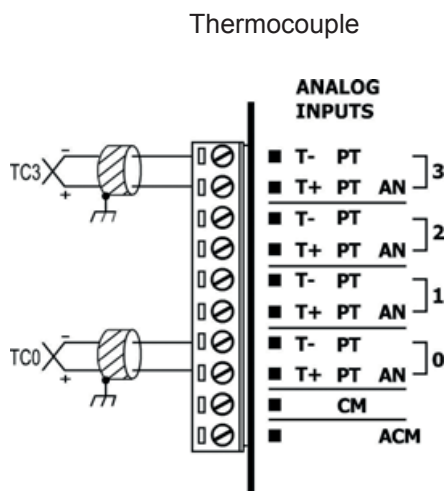
1. Wire one lead of each RTD input to the common signal (CM) as shown below.
- 4 wire PT100 can be used by leaving one of the sensor leads unconnected.

PT100



### Thermocouple Inputs

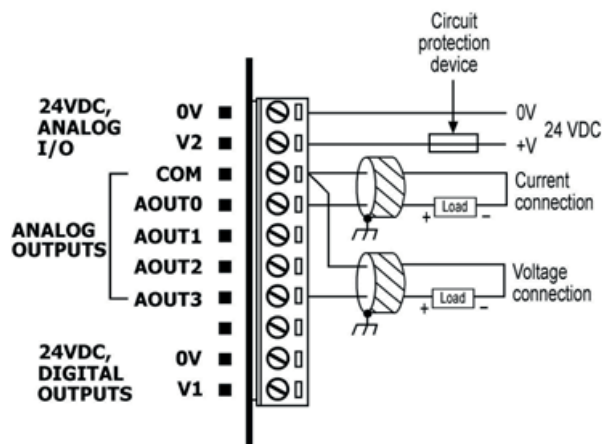
- Supported thermocouple types include B, E, J, K, N, R, S, and T, in accordance with software and jumper settings. See table Thermocouple Input Ranges, on page 15.
- Inputs may be set to mV by software settings (Hardware Configuration); note that in order to set mV inputs, thermocouple jumper settings are used.



### Analog Outputs

- Shields should be earthed, connected to the earth of the cabinet.
- An output can be wired to either current or voltage.
  - Use the appropriate wiring as shown below.
  - Open the device and set the jumpers according to the instructions beginning on page 8.
- To ensure proper performance, a warm-up period of a half an hour is recommended.

current/voltage



## Changing Jumper Settings

To access the jumpers, you must remove the snap-in I/O module from the controller, and then remove the module's PCB board. Before you begin, turn off the power supply, disconnect and dismount the controller.

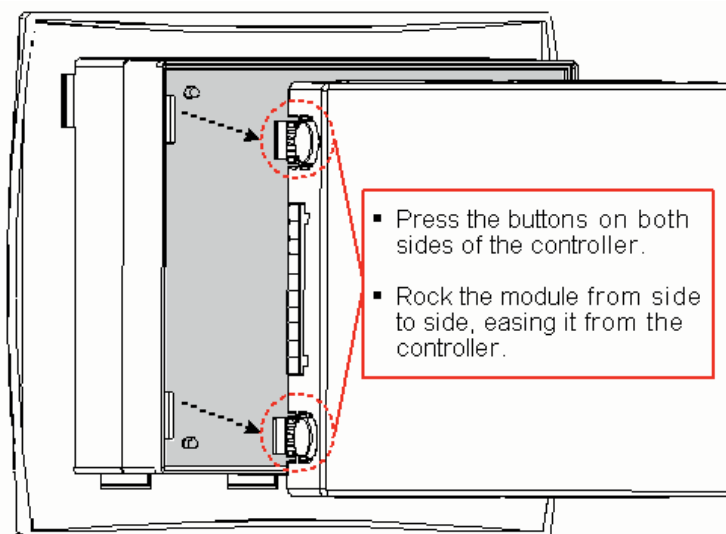


- Before performing these actions, touch a grounded object to discharge any electrostatic charge.
- Avoid touching the PCB board directly by holding the PCB board by its connectors.

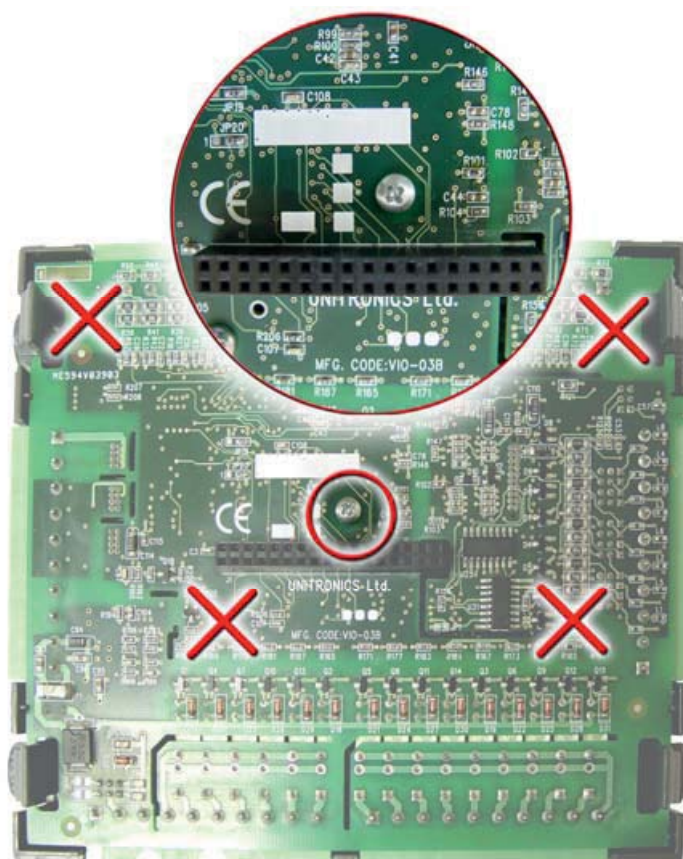
### Accessing the Jumpers

First, remove the snap-in module.

1. Locate the 4 buttons on the sides of the module, two on either side. Press the 2 buttons on either side of the module as shown, and hold them down to open the locking mechanism.
2. Gently rock the module from side to side, easing the module from the controller.

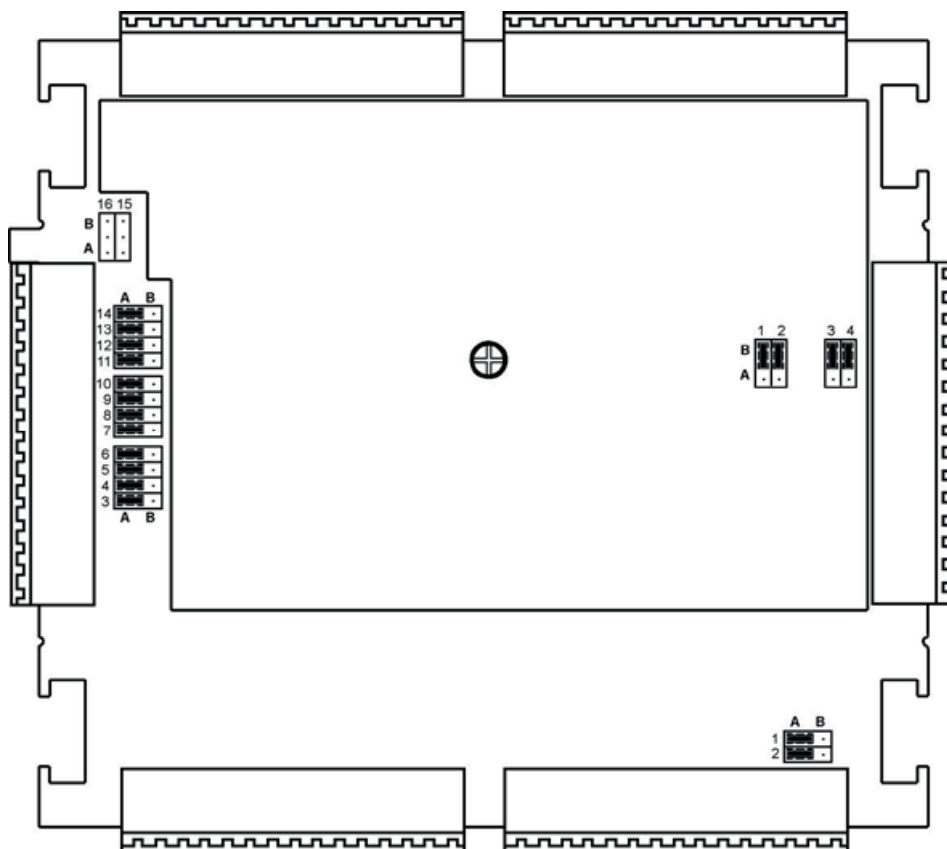


3. Using a Philips screwdriver, remove the center screw, shown in the figure below, from the module's upper PCB board. **Do not remove any other screws.**
4. Holding the PCB board by its edges, gently lift it out of the module.





Select the desired function by changing the jumper settings according to the figure and tables shown below.



### Analog Input Jumpers

|                         |                       | Jumper # | Voltage* | Current | T/C or mV | PT100 |
|-------------------------|-----------------------|----------|----------|---------|-----------|-------|
| <b>Bottom PCB board</b> | <b>Analog input 3</b> | 14       | A        | B       | B         | A     |
|                         |                       | 13       | A        | B       | B         | A     |
|                         |                       | 12       | A        | A       | B         | B     |
|                         | <b>Analog input 2</b> | 11       | A        | B       | B         | A     |
|                         |                       | 10       | A        | B       | B         | A     |
|                         |                       | 9        | A        | A       | B         | B     |
|                         | <b>Analog input 1</b> | 8        | A        | B       | B         | A     |
|                         |                       | 7        | A        | B       | B         | A     |
|                         |                       | 6        | A        | A       | B         | B     |
| <b>Analog input 0</b>   | 5                     | A        | B        | B       | A         |       |
|                         | 4                     | A        | B        | B       | A         |       |
|                         | 3                     | A        | A        | B       | B         |       |

### Digital Output Jumpers

|   |                         | Jumper # | PNP* | NPN |
|---|-------------------------|----------|------|-----|
| Note that Jumpers #15 & 16 are not used | <b>Digital Output 0</b> | 1        | A    | B   |
|   | <b>Digital Output 1</b> | 2        | A    | B   |

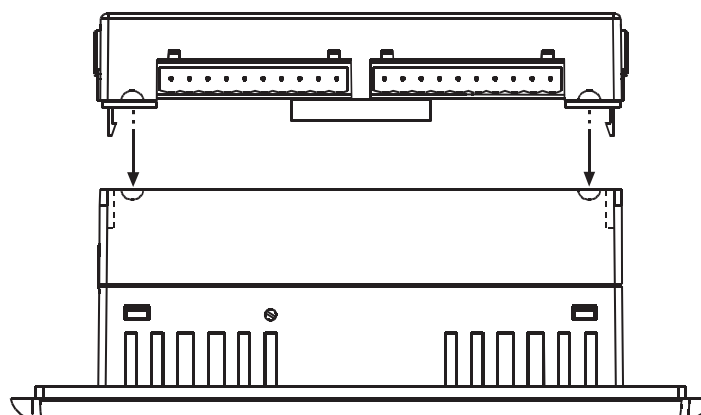
### Analog Output Jumpers

|                      |                 | Jumper # | Current | Voltage* |
|----------------------|-----------------|----------|---------|----------|
| <b>Top PCB board</b> | Analog Output 0 | 1        | A       | B        |
|                      | Analog Output 1 | 2        | A       | B        |
|                      | Analog Output 2 | 3        | A       | B        |
|                      | Analog Output 3 | 4        | A       | B        |

\* Default factory setting

### Reassembling the controller

1. Return the PCB board to the module and secure the center screw.
2. Next, reinstall the module. Line the circular guidelines on the controller up with the guidelines on the Snap-in I/O Module as shown below.
3. Apply even pressure on all 4 corners until you hear a distinct 'click'. The module is now installed. Check that all sides and corners are correctly aligned.



## V200-18-E3XB Technical Specifications

### Digital Inputs

|  |  |
|--|--|
| Number of inputs                               | 18 (in two groups)   |
| Input type                                     | pnp (source) or npn (sink)   |
| Galvanic isolation                             |  |
| Digital inputs to bus                          | Yes  |
| Digital inputs to digital inputs in same group | No   |
| Group to group, digital inputs                 | Yes  |
| Nominal input voltage                          | 24VDC  |
| Input voltage                                  |  |
| pnp (source)                                   | 0-5VDC for Logic '0'<br>17-28.8VDC for Logic '1'   |
| npn (sink)                                     | 17-28.8VDC for Logic '0'<br>0-5VDC for Logic '1'   |
| Input current                                  | 6mA@24VDC for inputs #4 to #17<br>8.8mA@24VDC for inputs #0 to #3  |
| Response time                                  | 10mSec typical   |
| High speed inputs                              | Specifications below apply when these inputs are wired for use as a high-speed counter input/shaft encoder. See Notes 1 and 2. |
| Resolution                                     | 32-bit   |
| Frequency                                      | 10kHz maximum  |
| Minimum pulse width                            | 40µs   |

### Notes:

- Inputs #0 and #2 can each function as either high-speed counter or as part of a shaft encoder. In each case, high-speed input specifications apply. When used as a normal digital input, normal input specifications apply.
- Inputs #1 and #3 can each function as either counter reset, or as a normal digital input; in either case, its specifications are those of a normal digital input. These inputs may also be used as part of a shaft encoder. In this case, high-speed input specifications apply.

### Digital Outputs

#### Digital Output's Power Supply

|  |                         |
|--|-------------------------|
| Nominal operating voltage                  | 24VDC                   |
| Operating voltage                          | 20.4 to 28.8VDC         |
| Quiescent current                          | 20mA@24VDC.             |
| Max. current consumption                   | 85mA@24VDC. See Note 3. |
| Galvanic isolation                         |                         |
| Digital power supply to bus                | Yes                     |
| Digital power supply to relay outputs      | Yes                     |
| Digital power supply to transistor outputs | No                      |

### Notes:

- Maximum current consumption does not provide for PNP output requirements. The additional current requirement of PNP outputs must be added.

**Relay Outputs**

|                               |  |
|-------------------------------|--|
| Number of outputs             | 15 relays (in two groups). See Note 4.   |
| Output type                   | SPST-NO (Form A)   |
| Isolation                     | By relay   |
| Type of relay                 | Tyco PCN-124D3MHZ or compatible  |
| Outputs' power supply         | See Digital Output's Power Supply above  |
| Galvanic isolation            |  |
| Relay outputs to bus          | Yes  |
| Group to group, relay outputs | Yes  |
| Relay to transistor outputs   | Yes  |
| Output current                | 3A maximum per output (resistive load)<br>8A maximum total for common (resistive load) |
| Rate voltage                  | 250VAC / 30VDC   |
| Minimum load                  | 1mA@5VDC   |
| Life expectancy               | 100k operations at maximum load  |
| Response time                 | 10mS (typical)   |
| Contact protection            | External precautions required (see Increasing Contact Life Span, p.4)                  |

**Notes:**

- Outputs #2,3,4,5,6 and 7 share a common signal. Outputs #8,9,10,11,12,13,14,15 and 16 share a common signal

**Transistor Outputs**

|  |   |
|--|---|
| Number of outputs                        | 2, high-speed. Each can be individually set as pnp (source) or npn (sink) via wiring and jumper settings. See Note 5. |
| Output type                              | pnp: P-MOSFET (open drain)<br>npn: N-MOSFET (open drain)  |
| Galvanic isolation                       |   |
| Transistor outputs to bus                | Yes   |
| Transistor outputs to transistor outputs | No  |
| Transistor outputs to relay outputs      | Yes   |
| Output current                           | pnp: 0.5A maximum per output<br>npn: 50mA maximum per output  |
| Maximum frequency                        | <u>Resistive load</u><br>pnp: 2kHz<br>npn: 50kHz<br><u>Inductive load</u><br>0.5Hz                                    |
| ON voltage drop                          | pnp: 0.5VDC maximum<br>npn: 0.4VDC maximum  |
| Short circuit protection                 | Yes (pnp only)  |
| pnp (source) power supply                | See Digital Output's Power Supply above   |
| npn (sink) power supply                  |   |
| operating voltage                        | 3.5V to 28.8VDC,<br>unrelated to the voltage of either the I/O module or the controller                               |

**Notes:**

- Both transistor outputs may be used as high-speed outputs.

**Analog I/O's Power Supply**

|                                       |                 |
|---------------------------------------|-----------------|
| Nominal operating voltage             | 24VDC           |
| Operating voltage                     | 20.4 to 28.8VDC |
| Quiescent current                     | 70mA@24VDC      |
| Max. current consumption              | 130mA@24VDC     |
| Galvanic isolation                    |                 |
| Analog power supply to bus            | Yes             |
| Analog power supply to analog inputs  | Yes             |
| Analog power supply to analog outputs | Yes             |

**Analog/ PT100/ TC Inputs**

|                  |   |
|------------------|---|
| Number of inputs | 4   |
| Type of input    | Set via appropriate wiring and jumper settings. |

**Analog Inputs Power Supply**

|  |     |
|--|-----|
| Galvanic isolation                           |     |
| Analog/PT/TC inputs to bus                   | Yes |
| Analog/PT/TC inputs to analog outputs        | Yes |
| Analog /PT/TC inputs to Analog /PT/TC inputs | No  |

**Analog inputs**

|                             |  |
|-----------------------------|--|
| Input range                 | 0-10V, 0-20mA , 4-20mA                           |
| Power supply                | See Analog I/O's Power Supply above              |
| Conversion method           | Successive approximation                         |
| Resolution at 0-10V, 0-20mA | 14-bit (16384 units). See Note 6.                |
| Resolution at 4-20mA        | 3277 to 16384 (13107 units). See Note 6.         |
| Conversion time             | Synchronized to cycle time                       |
| Input impedance             | >1M $\Omega$ —voltage<br>121.5 $\Omega$ —current |
| Absolute maximum rating     | $\pm$ 20V—voltage<br>$\pm$ 40mA—current          |
| Full-scale error            | $\pm$ 0.4%                                       |
| Linearity error             | $\pm$ 0.04%                                      |
| Status indication           | Yes. See Note 7.                                 |

**Notes:**

- 12 or 14-bit resolution may be selected via software.
- The analog value can indicate faults as shown below:

| <u>Value</u> | <u>Possible Cause</u>  |
|--------------|--|
| 16384        | Input value deviates <b>slightly above</b> the input range   |
| 32767        | -Input value deviates <b>greatly above</b> or <b>below</b> the input range<br>-Power supply disconnected |

**PT100 inputs**

|                             |  |
|-----------------------------|--|
| Input range                 | -200 to 600°C/-328 to 1100°F. 1 to 320Ω. See Note 8.         |
| Conversion method           | Voltage to frequency   |
| Resolution                  | 0.1°C/0.1°F  |
| Conversion time             | 200mS minimum per channel, depending on software filter type |
| Input impedance             | >10MΩ  |
| Auxillary current for PT100 | 150μA typical  |
| Full-scale error            | ±0.4%  |
| Linearity error             | ±0.04%   |
| Status indication           | Yes. See Note 9.   |

**Notes:**

- The device can also measure resistance with the range of 1-320 Ω at a resolution of 0.1 Ω.
- The analog value can indicate faults as shown below:

| <u>Value</u> | <u>Possible Cause</u>  |
|--------------|--|
| 32767        | - Sensor is not connected to input<br>- Value exceeds permissible range<br>- Power supply disconnected |
| -32767       | Sensor is short-circuited  |

**Thermocouple inputs**

|                                  |  |
|----------------------------------|--|
| Input range                      | As shown in the table on page 15. See Note 10.               |
| Conversion method                | Voltage to frequency   |
| Resolution                       | 0.1°C/0.1°F maximum  |
| Conversion time                  | 100mS minimum per channel, depending on software filter type |
| Input impedance                  | >10MΩ  |
| Cold junction compensation       | Local, automatic   |
| Cold junction compensation error | ±1.5°C / ±2.7°F maximum                                      |
| Absolute maximum rating          | ±0.6VDC  |
| Full-scale error                 | ±0.4%  |
| Linearity error                  | ±0.04%   |
| Warm-up time                     | ½ hour typically, ±1°C/±1.8°F repeatability                  |
| Status indication                | Yes. See Note 11.  |

**Notes:**

- The device can also measure voltage within the range of -5 to 56mV, at a resolution of 0.01mV. The device can also measure raw value frequency at a resolution of 14-bits(16384)
- The analog value can indicate faults as shown below:

| <u>Value</u> | <u>Possible Cause</u>   |
|--------------|---|
| 32767        | - Sensor is not connected to input<br>- Sensor value exceeds the maximum value<br>- Power supply disconnected |
| -32767       | Sensor value is under the minimum value   |

Table 1: Thermocouple input ranges

| Type | Temperature range                  | Wire Color      |                  |
|------|------------------------------------|-----------------|------------------|
|      |                                    | ANSI (USA)      | BS 1843 (UK)     |
| mV   | -5 to 56mV                         | -               | -                |
| B    | 200 to 1820°C<br>(300 to 3276°F)   | +Grey<br>-Red   | +None<br>-Blue   |
| E    | -200 to 750°C<br>(-328 to 1382°F)  | +Violet<br>-Red | +Brown<br>-Blue  |
| J    | -200 to 760°C<br>(-328 to 1400°F)  | +White<br>-Red  | +Yellow<br>-Blue |
| K    | -200 to 1250°C<br>(-328 to 2282°F) | +Yellow<br>-Red | +Brown<br>-Blue  |
| N    | -200 to 1300°C<br>(-328 to 2372°F) | +Orange<br>-Red | +Orange<br>-Blue |
| R    | 0 to 1768°C<br>(32 to 3214°F)      | +Black<br>-Red  | +White<br>-Blue  |
| S    | 0 to 1768°C<br>(32 to 3214°F)      | +Black<br>-Red  | +White<br>-Blue  |
| T    | -200 to 400°C<br>(-328 to 752°F)   | +Blue<br>-Red   | +White<br>-Blue  |

### **Analog Outputs**

|                   |   |
|-------------------|---|
| Number of outputs | 4 (single-ended)                            |
| Output range      | 0-10V, 4-20mA. See Note 12.                 |
| Resolution        | 12-bit (4096 units)                         |
| Conversion time   | Synchronized to scan time.                  |
| Load impedance    | 1kΩ minimum—voltage<br>500Ω maximum—current |

### Galvanic isolation

|  |     |
|--|-----|
| Analog outputs to bus                    | Yes |
| Analog outputs to<br>Analog/PT/TC inputs | Yes |
| Analog outputs to analog<br>outputs      | No  |

Linearity error ±0.1%

Operational error limits ±0.2%

### **Notes:**

12. Note that the range of each I/O is defined by wiring, jumper settings, and within the controller's software.

### **Environmental**

|                        |                               |
|------------------------|-------------------------------|
|                        | IP20 / NEMA1                  |
| Operating temperature  | 0° to 45°C (32° to 113°F)     |
| Storage temperature    | -20° to 60° C (-4° to 140°F)  |
| Relative Humidity (RH) | 5% to 90% (non-condensing)    |
| Dimensions (WxHxD)     | 138x23x123mm (5.43x0.9x4.84") |
| Weight                 | 279g (9.87 oz)                |

## About Unitronics

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Unitronics' OPLC controllers combine full-function PLCs and HMI operating panels into single, compact units. These HMI + PLC devices are programmed in a single, user-friendly environment. Our clients save I/O points, wiring, space, and programming time; elements that translate directly into cost-efficiency.

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